

A simple and complete model theory for intensional and extensional untyped λ -equality

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Abstract

We present a sound and complete model theory for theories of β -reduction with or without η -expansion. We then show in what conditions we obtain models of β -equality and $\beta\eta$ -equality.

1 Introduction

We extend the method of [GG10] by which we are able to interpret λ -terms compositionally on ‘possible world’ structures. The simplicity of the structures is striking, moreover, they provide us with a surprising richness of interpretations of function abstraction and application. Our primary goal is to show how the models can differentiate between *extensional* and *intensional* λ -equality, and provide semantic characterisation (i.e. completeness) theorems for both. We shall then hint at how richer λ -languages can be interpreted.

The key idea in this paper is a class of models, presented in Section 2.2, although an important syntactic consideration is required first in Section 2.1. These ideas bear some similarity to the reduction models of [Sel03] in that they get us as far as λ -reduction only. Then, in Section 4 we make use of the results of the earlier sections to provide a characterisation theorem for λ -equality (both with and without η -equality, i.e. extensional and intensional). We can then use this characterisation to comment on the issue of *order-incompleteness*.

2 The models, computation, logic

2.1 The language and logic

Definition 2.1. Fix a countably infinite set of **variables**.

Define a language \mathcal{L}_λ of λ -terms by:

$$t ::= x \mid \lambda x.t \mid t \cdot t$$

λx binds in $\lambda x.t$. For example, x is bound (not free) in $\lambda x.x \cdot y$.

We write $t[x/s]$ for the usual capture-avoiding substitution. For example, $(\lambda z.y)[y/x] = \lambda z.x$, and $(\lambda x.y)[y/x] = \lambda z.x$ where z is an arbitrary fresh variable.

We write $t[x:-s]$ for the (unusual) non-capture avoiding substitution. For example, $(\lambda x.x)[x:-y] = \lambda x.y$, $(\lambda x.y)[y:-x] = \lambda x.x$ and $x[y:-t] = x$.

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| | |
|---|--|
| Let x occur free <i>only once</i> in \mathfrak{t} . | |
| $(\beta) \quad \mathfrak{t}[x:-(\lambda x.s)\cdot\mathfrak{r}] \longrightarrow_{\Gamma} \mathfrak{t}[x:-s[x/\mathfrak{r}]]$ | $(ass) \quad \mathfrak{t}[x:-s] \longrightarrow_{\Gamma} \mathfrak{t}[x:-\mathfrak{r}] \quad (\langle s, \mathfrak{r} \rangle \in \Gamma)$ |
| $(\alpha) \quad \mathfrak{t}[x:-\lambda y.s] \longrightarrow_{\Gamma} \mathfrak{t}[x:-\lambda z.s[y/z]]$ | |

Figure 1: λ -reduction for \mathcal{L}_{λ}

We now turn to λ -reduction. We shall define a basic relation on terms that follows the familiar reduction rule of β -contraction. To help with the completeness theorem of Section 3 we will need to consider a conservative extension of the familiar λ -calculus (Definition 2.4). To facilitate the proof that this extension really is conservative (Theorem 2.7), we present the λ -calculus in the non-axiomatic style of [HS08, Def. 1.24]. It is important for us to consider not merely the relation of λ -reduction, but a relation of λ -reduction *with assumptions*. We do this so we can consider the theory of λ -equality as an extension of the theory of λ -reduction. Our models shall initially model only be sound for β -reduction and η -expansion. We can then begin our characterisation of $\beta\eta$ -equality by considering the subclass of these models that also validate β -expansion and η -reduction. We therefore need to define some basic, and familiar, rules of λ -reduction but allow for a set of assumed additional reductions (we do not seek to study the syntactic properties of a general calculus of λ -reduction with assumptions in this paper).

Definition 2.2. Let Γ be a set of pairs of terms of \mathcal{L}_{λ} . We define a **reduction relation** \longrightarrow_{Γ} on terms of \mathcal{L}_{λ} using Figure 1. A **derivation** is a sequence of terms $\mathfrak{t}_1, \dots, \mathfrak{t}_n$ such that $\mathfrak{t}_i \longrightarrow_{\Gamma} \mathfrak{t}_{i+1}$ for each $1 \leq i < n$.

Remark 2.3. If $\Gamma = \emptyset$ then \longrightarrow_{Γ} is the familiar relation of untyped β -reduction.

Definition 2.4. Define \mathcal{L}_{λ}^* by: $\mathfrak{t} ::= x \mid \lambda x.t \mid \mathfrak{t}\cdot\mathfrak{t} \mid \mathfrak{t} * \mathfrak{t}$

Definition 2.5. Let Γ be a set of pairs of terms of \mathcal{L}_{λ} (*not* \mathcal{L}_{λ}^*). Define a reduction relation \Longrightarrow_{Γ} on terms of \mathcal{L}_{λ}^* using Figure 2. Again, a **derivation** is a sequence of terms $\mathfrak{t}_1, \dots, \mathfrak{t}_n$ such that $\mathfrak{t}_i \Longrightarrow_{\Gamma} \mathfrak{t}_{i+1}$ for each $1 \leq i < n$.

Remark 2.6. Notice that we do not allow terms unique to \mathcal{L}_{λ}^* to be assumptions in derivations. There are two reasons for this. Firstly, the paper is initially concerned with characterising reduction and equality only in the more familiar language \mathcal{L}_{λ} , and \mathcal{L}_{λ}^* is merely a means to that end. Allowing assumed reductions for \mathcal{L}_{λ}^* adds needless complexity to Theorem 2.7. Secondly, a further aim is to show that β -equality (i.e. β -expansion and contraction) is complete for models with a nontrivial ordering relation on them. The fact that β -equality holds for \mathcal{L}_{λ} but not for \mathcal{L}_{λ}^* helps to emphasise this.

Theorem 2.7. *If \mathfrak{t}_1 and \mathfrak{t}_2 are terms of \mathcal{L}_{λ} then $\mathfrak{t}_1 \Longrightarrow_{\Gamma} \mathfrak{t}_2$ implies $\mathfrak{t}_1 \longrightarrow_{\Gamma} \mathfrak{t}_2$. In other words \Longrightarrow_{Γ} is conservative over \longrightarrow_{Γ} .*

Proof. See the technical appendix A.1 □

2.2 Frames and interpreting λ -terms

Definition 2.8. If W is a set, write $\mathcal{P}(W)$ for the set of subsets of W .

An **intensional frame** F is a 4-tuple (W, \bullet, \circ, H) where:

| | |
|--|--|
| Let x occur free <i>only once</i> in \mathfrak{t} . | |
| $(\beta) \quad \mathfrak{t}[x:-(\lambda x.s)\cdot r] \Longrightarrow_{\Gamma} \mathfrak{t}[x:-s[x/r]]$ | $(ass) \quad \mathfrak{t}[x:-s] \Longrightarrow_{\Gamma} \mathfrak{t}[x:-r] \quad \langle s, r \rangle \in \Gamma$ |
| $(\alpha) \quad \mathfrak{t}[x:-\lambda y.s] \Longrightarrow_{\Gamma} \mathfrak{t}[x:-\lambda z.s[y/z]]$ | |
| $(\beta^*) \quad \mathfrak{t}[x:-(\lambda x.s) * r] \Longrightarrow_{\Gamma} \mathfrak{t}[x:-s[x/r]]$ | $(sub) \quad \mathfrak{t}[x:-s \cdot r] \Longrightarrow_{\Gamma} \mathfrak{t}[x:-s * r]$ |
| $(\eta^*) \quad \mathfrak{t}[x:-s] \Longrightarrow_{\Gamma} \mathfrak{t}[x:-\lambda y.(s * y)] \quad (y \text{ not free in } s)$ | |

Figure 2: λ -reduction for \mathcal{L}_{λ}^*

- W a set of **worlds**,
- \bullet and \circ are functions from $W \times W$ to $\mathcal{P}(W)$ such that $\bullet \subseteq \circ$.
- $H \subseteq \mathcal{P}(W)$.

Remark 2.9. Subsets of W will serve as denotations of λ -terms (Definition 2.12) and $H \subseteq \mathcal{P}(W)$ (H for ‘Henkin’) plays a similar role to the structure of Henkin models for higher-order logic [BBK04, Hen50, Sha00]. This makes our completeness results possible and is a famous issue for second- and higher-order logics. Powersets are too large; for completeness results to be possible we must cut them down — at least when we quantify. This is why in Definition 2.12, the binders restrict quantification from $\mathcal{P}(W)$ down to H .

The reader familiar with modal logic can think of \bullet and \circ as ternary ‘accessibility relations’ R_{\bullet} and R_{\circ} such that $R_{\bullet} w_1 w_2 w_3$ if and only if $w_3 \in w_1 \bullet w_2$ (and similarly for R_{\circ}). We can also think of \bullet and \circ as non-deterministic ‘application’ operations, but note that intensional frames are not applicative structures — an applicative structure would map $W \times W$ to W , whereas in the case of intensional frames, $W \times W$ maps to $\mathcal{P}(W)$.

Definition 2.10. Let $F = (W, \bullet, \circ, H)$ be an intensional frame and $S_1, S_2 \subseteq W$ and $w \in W$. Then the functions \bullet and \circ induce functions from $W \times \mathcal{P}(W)$ and $\mathcal{P}(W) \times \mathcal{P}(W)$ to $\mathcal{P}(W)$ by: $w \bullet S = \bigcup \{w \bullet w' \mid w' \in S\}$ and $S_1 \bullet S_2 = \bigcup \{w_1 \bullet w_2 \mid w_1 \in S_1, w_2 \in S_2\}$ (and similarly for \circ).

Definition 2.11. Suppose $F = (W, \bullet, \circ, H)$ is a frame. A **valuation** (to F) is a map from variables to sets of worlds (elements of $\mathcal{P}(W)$) that are in H . v will range over valuations.

If x is a variable, $h \in H$, and v is a valuation, then write $v[x \mapsto h]$ for the valuation mapping x to h and mapping y to $v(y)$ for any other y .

Definition 2.12. Define the **denotation** of \mathfrak{t} inductively by:

$$\begin{aligned} \llbracket x \rrbracket^v &= v(x) & \llbracket \mathfrak{t} \cdot \mathfrak{s} \rrbracket^v &= \llbracket \mathfrak{t} \rrbracket^v \bullet \llbracket \mathfrak{s} \rrbracket^v & \llbracket \mathfrak{t} * \mathfrak{s} \rrbracket^v &= \llbracket \mathfrak{t} \rrbracket^v \circ \llbracket \mathfrak{s} \rrbracket^v \\ \llbracket \lambda x. \mathfrak{t} \rrbracket^v &= \{w \mid w \circ h \subseteq \llbracket \mathfrak{t} \rrbracket^{v[x \mapsto h]} \text{ for all } h \in H\} \end{aligned}$$

Remark 2.13. By elementary set theory: $\llbracket \lambda x. \mathfrak{t} \rrbracket^v = \bigcap_{h \in H} \{w \mid w \circ h \subseteq \llbracket \mathfrak{t} \rrbracket^{v[x \mapsto h]}\}$

We are particularly interested in frames where the denotation of every λ -term is a member of H . This is because Definition 2.12 interprets λ as a kind of quantifier over all members of H . β -reduction then becomes a form of universal instantiation and so requires that every possible instantiation (i.e. every term denotation) is a member of H .

Definition 2.14. A frame is **faithful** when for every v and every \mathfrak{t} , $\llbracket \mathfrak{t} \rrbracket^v \in H$.

Lemma 2.15. 1. If x is not free in \mathfrak{t} , then for any $h \in H$, $\llbracket \mathfrak{t} \rrbracket^v = \llbracket \mathfrak{t} \rrbracket^{v[x \mapsto h]}$.

$$2. \llbracket \mathbf{t}[x/s] \rrbracket^v = \llbracket \mathbf{t} \rrbracket^{v[x \mapsto [s]^v]}$$

Proof. Both parts follow by easy inductions on \mathbf{t} . \square

Theorem 2.16. *If we interpret \longrightarrow_Γ as subset inclusion then all the rules of Figure 2 are sound for faithful intensional frames.*

Proof. By routine calculations from the definitions. See the technical appendix A.2 \square

2.3 Soundness

Definition 2.17. – A **model** M is a pair $\langle F, v \rangle$ where F is a faithful intensional frame and v is a valuation on F .

– Say a model is Γ -**sensitive** if $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ for every $\langle \mathbf{t}, \mathbf{s} \rangle \in \Gamma$.

– Say a frame F is Γ -**sensitive** if $\langle F, v \rangle$ is Γ -sensitive for every v .

Remark 2.18. We could have defined a model as a pair $\langle F, v \rangle$ where $F = \langle W, \bullet, \circ, H \rangle$ is a (possibly not faithful) frame and v is a valuation on F such that $\llbracket \mathbf{t} \rrbracket^v \in H$ for every \mathbf{t} . But since the completeness theorem 3.9 holds for the stronger notion of a model we shall use that.

Lemma 2.19. \bullet and \circ are **monotone**. That is, $h_1 \subseteq h_2$ implies $h \bullet h_1 \subseteq h \bullet h_2$ and $h_1 \bullet h \subseteq h_2 \bullet h$ for any h , and similarly for \circ .

Lemma 2.20. *If $\llbracket \mathbf{s} \rrbracket^v \subseteq \llbracket \mathbf{r} \rrbracket^v$ for all v on some faithful F , then $\llbracket \mathbf{t}[x:-\mathbf{s}] \rrbracket^v \subseteq \llbracket \mathbf{t}[x:-\mathbf{r}] \rrbracket^v$*

Theorem 2.21. $\mathbf{t} \Longrightarrow_\Gamma \mathbf{s}$ implies $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ in all Γ -sensitive models M .

Proof. Theorem 2.16 entails that each rule of Figure 2 holds in all models, and by definition, if $\langle \mathbf{t}, \mathbf{s} \rangle \in \Gamma$ then $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ in all Γ -sensitive models. The result then follows by Lemma 2.20. \square

3 Completeness for λ -reduction

We must show that if $\mathbf{t} \not\longrightarrow_\Gamma \mathbf{s}$ then there is a Γ -sensitive model M where $\llbracket \mathbf{t} \rrbracket^v \not\subseteq \llbracket \mathbf{s} \rrbracket^v$. We first show that $\mathbf{t} \not\longrightarrow_\Gamma \mathbf{s}$ implies such an M exists if $\mathbf{t}, \mathbf{s} \in \mathcal{L}_\lambda$, and then we appeal to Theorem 2.7.

First we add infinitely many new constant symbols $c_1, c_2 \dots$ to the language \mathcal{L}_λ^* . Since the language is countable we can enumerate its terms $\mathbf{t}_1, \mathbf{t}_2 \dots$, which may contain the new constants, and the new constants alone $c_1, c_2 \dots$. We describe a one-one function f from terms to constants.

$f(\mathbf{t}_i) = c_j$ where j is the least number such that $j > i$ and c_j does not occur in \mathbf{t}_i
nor is the value under f of any \mathbf{t}_k for $k < i$.

Thus f is a one-one function that assigns a distinct ‘fresh’ constant to each term of the language. Thus $f(\mathbf{t})$ is a constant that ‘names’ \mathbf{t} . These play the role of witness constants in the construction of the canonical frame in Theorem 3.7. The $f(\mathbf{t})$ also help us carry out inductions on the size of λ -terms, as $\mathbf{t}[x/f(\mathbf{s})]$ is smaller than $\lambda x.\mathbf{t}$ even if $\mathbf{t}[x/s]$ might not be.

Definition 3.1. Let $\zeta_f = \{ \langle \mathbf{t}, f(\mathbf{t}) \rangle \mid \mathbf{t} \text{ is a term} \} \cup \{ \langle f(\mathbf{t}), \mathbf{t} \rangle \mid \mathbf{t} \text{ is a term} \}$. Write $\mathbf{t} \Longrightarrow_\Gamma^{\zeta_f} \mathbf{s}$ when $\zeta_f \subseteq \Gamma$ and $\mathbf{t} \Longrightarrow_\Gamma \mathbf{s}$.

Lemma 3.2. *If $\mathbf{t} \Longrightarrow_\Gamma^{\zeta_f} \mathbf{s}$ and neither \mathbf{s} or \mathbf{t} contain any of the new constants $c_1, c_2 \dots$, then $\mathbf{t} \Longrightarrow_\Gamma \mathbf{s}$.*

Proof. f is defined in terms of an enumeration such that \mathbf{r} always precedes $f(\mathbf{r})$. Thus if we repeatedly substitute each instance of $f(\mathbf{r})$ with \mathbf{r} in a derivation, eventually all will be eliminated. But then instances of (ass) depending on ζ_f become trivial reductions $\mathbf{r} \Longrightarrow_{\Gamma}^{\zeta_f} \mathbf{r}$ which can be removed without affecting the rest of the derivation. Certainly the first and final terms \mathbf{t} and \mathbf{s} are unaffected as they never contained any $f(\mathbf{r})$ in the first place. \square

Definition 3.3. If \mathbf{t} is a term let $w_{\mathbf{t}} = \{\mathbf{s} \mid \mathbf{t} \Longrightarrow_{\Gamma}^{\zeta_f} \mathbf{s}\}$. Thus $w_{\mathbf{t}}$ is the closure of \mathbf{t} under $\Longrightarrow_{\Gamma}^{\zeta_f}$.

Definition 3.4. Define the **canonical λ -frame** $F_{\lambda} = \langle W_{\lambda}, \bullet_{\lambda}, \circ_{\lambda}, H_{\lambda} \rangle$:

$$\begin{aligned} W_{\lambda} &= \{w_{\mathbf{t}} \mid \mathbf{t} \in \mathcal{L}_{\lambda}^*\} & H_{\lambda} &= \{\{w_{\mathbf{s}} \in W_{\lambda} \mid \mathbf{t} \in w_{\mathbf{s}}\} \mid \mathbf{t}, \mathbf{s} \in \mathcal{L}_{\lambda}^*\} \\ w_{\mathbf{t}} \bullet_{\lambda} w_{\mathbf{s}} &= \{w \in W_{\lambda} \mid \mathbf{t} \cdot \mathbf{s} \in w\} & w_{\mathbf{t}} \circ_{\lambda} w_{\mathbf{s}} &= \{w \in W_{\lambda} \mid \mathbf{t} * \mathbf{s} \in w\} \end{aligned}$$

Definition 3.5. Given $F_{\lambda} = \langle W_{\lambda}, \bullet_{\lambda}, \circ_{\lambda}, H_{\lambda} \rangle$ and a term \mathbf{t} of \mathcal{L}_{λ}^* . Let $\|\mathbf{t}\| = \{w \in W_{\lambda} \mid \mathbf{t} \in w\}$. Note that $H_{\lambda} = \{\|\mathbf{t}\| \mid \mathbf{t} \in \mathcal{L}_{\lambda}^*\}$

Remark 3.6. Given (sub) it is easy to see that $\bullet_{\lambda} \subseteq \circ_{\lambda}$. To see how \bullet_{λ} and \circ_{λ} come apart consider $w_{\lambda y.(x \cdot y)}$, $w_{\mathbf{z}}$ and $w_{\mathbf{x} \cdot \mathbf{z}}$. Then $w_{\mathbf{x} \cdot \mathbf{z}} \in w_{\lambda y.(x \cdot y)} \circ w_{\mathbf{z}}$, but since $\mathbf{x} \cdot \mathbf{z} \not\Longrightarrow_{\Gamma} \lambda y.(x \cdot y) \cdot \mathbf{z}$, $w_{\mathbf{x} \cdot \mathbf{z}} \notin w_{\lambda y.(x \cdot y)} \bullet w_{\mathbf{z}}$.

Theorem 3.7. Let F_{λ} be the canonical intensional λ -frame (Definition 3.4) and let $v(\mathbf{r}) = \|\mathbf{r}\|$ for any variable or constant \mathbf{r} . Then for any term \mathbf{t} , $\llbracket \mathbf{t} \rrbracket^v = \|\mathbf{t}\|$.

Proof. By induction on \mathbf{t} we show that $w \in \|\mathbf{t}\|$ (i.e. $\mathbf{t} \in w$) if and only if $w \in \llbracket \mathbf{t} \rrbracket^v$. Details are in the technical appendix A.3 \square

Lemma 3.8. If there is a valuation v on a frame F such that $\{\llbracket \mathbf{t} \rrbracket^v \mid \mathbf{t} \text{ is a term}\} = H$, then F is faithful. Hence the canonical frame F_{λ} is faithful.

Proof. See the technical appendix A.4. \square

Theorem 3.9. $\mathbf{t} \Longrightarrow_{\Gamma} \mathbf{s}$ if and only if $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ for all Γ -sensitive models.

Proof. The left-right direction is Theorem 2.21.

If $\mathbf{t} \not\Longrightarrow_{\Gamma} \mathbf{s}$ then, by Theorem 2.7, $\mathbf{t} \not\Longrightarrow_{\Gamma} \mathbf{s}$ and so $\mathbf{s} \notin w_{\mathbf{t}}$ in F_{λ} . Therefore $\|\mathbf{t}\| \not\subseteq \|\mathbf{s}\|$ and so by Theorem 3.7 there is a valuation v such that $\llbracket \mathbf{t} \rrbracket^v \not\subseteq \llbracket \mathbf{s} \rrbracket^v$ on the canonical frame F_{λ} . Furthermore, by Lemma 3.8, F_{λ} is faithful, and since $\|\mathbf{r}_1\| \subseteq \|\mathbf{r}_2\|$ for $\langle \mathbf{r}_1, \mathbf{r}_2 \rangle \in \Gamma$ it follows that $M_{\lambda} = \langle F_{\lambda}, v \rangle$ is Γ -sensitive. \square

Definition 3.10. An **extensional frame** is an intensional frame where $\bullet = \circ$, we may define them simply as a triple $\langle W, \bullet, H \rangle$

Corollary 3.11. Let $\Gamma = \{\langle \mathbf{t}[\mathbf{x}:-\mathbf{r}], \mathbf{t}[\mathbf{x}:-\lambda y.(\mathbf{r} \cdot y)] \rangle \mid \mathbf{r} \in \mathcal{L}_{\lambda} \text{ and } y \text{ is not free in } \mathbf{r}\}$. Then $\mathbf{t} \Longrightarrow_{\Gamma} \mathbf{s}$ if and only if $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ for any faithful extensional frame and any v .

Proof. For the left-right direction it is a simple matter to apply the reasoning of Theorem 2.21. For the right-left direction it is enough to note that:

$$\mathbf{t}[\mathbf{x}:-\mathbf{s} * \mathbf{r}] \xrightarrow{(ass)}_{\Gamma} \mathbf{t}[-\lambda y(\mathbf{s} \cdot y) * \mathbf{r}] \xrightarrow{(\beta^*)}_{\Gamma} \mathbf{t}[\mathbf{x}:-\mathbf{s} \cdot \mathbf{r}]$$

so in the construction of the canonical frame F_{λ} of Theorem 3.7, $\bullet_{\lambda} = \circ_{\lambda}$. \square

Remark 3.12. An extensional frame satisfies η -expansion. An intensional frame is like an extensional frame except with an additional ‘inner’ application function. We interpret λ in terms of the outer function and application in terms of the inner function to block η -expansion. η -expansion will prove very useful in constructing models of λ -equality in Section 4. But others have also noted good properties and justification in models for η -expansion [JG95].

4 Equality

Definition 4.1. Let $\beta = \{\langle \tau[x:-s[y/r]], \tau[x:-\lambda y.s.r] \rangle \mid \tau, s, r \in \mathcal{L}_\lambda\}$.

Corollary 4.2. When restricted to \mathcal{L}_λ , \implies_β is the familiar relation of (intensional) λ -equality, and by Theorem 3.9 is complete for β -sensitive models.

Corollary 4.2 is itself not so significant as it only tells us half the story about what these models look like, and does not tell us if there are any non-trivial ones. Of course, given independent nontriviality proofs for λ -equality,¹ we can use Theorem 3.9 to conclude that there are nontrivial β -sensitive models. This section is concerned with producing a purely semantic characterisation of β -sensitivity.

The strategy we shall employ is as follows. First we extend \mathcal{L}_λ and \mathcal{L}_λ^* with two constant symbols \mathbf{S}, \mathbf{K} and \mathbf{C} . We will use these symbols to stand in for constructions involving λ -expressions. So for example $\mathbf{K}\cdot\mathbf{z}$ will stand in for $(\lambda x \lambda y.x)\cdot\mathbf{z}$, and the former expression contains no instances of λ . This will allow us to work with certain complex λ -expressions as if they are free of the symbol λ and is particularly useful for a stronger form of induction which we shall use. Then, for each τ we describe a new term $[x]\tau$, built only out of application and the three new constants (effectively the familiar combinator abstraction of [HS08, p.26], but extended to a language that includes the λ -operator). Then, with the help of the completeness theorem 3.9, we describe conditions in which a model (or frame) entails that $\llbracket \tau[x/s] \rrbracket^v = \llbracket [x]\tau \cdot s \rrbracket^v$. It then turns out that $\llbracket [x]\tau \rrbracket^v \subseteq \llbracket \lambda x.\tau \rrbracket^v$ and we thereby obtain models of β -expansion

Definition 4.3. Let $\mathcal{L}_{\mathcal{X}\mathcal{C}}^*$ ($\mathcal{L}_{\mathcal{X}\mathcal{C}}$) be \mathcal{L}_λ^* (\mathcal{L}_λ) with new constant symbols $\mathbf{S}, \mathbf{K}, \mathbf{C}$.

Definition 4.4. When defining or proving a property of a term τ , we write ‘**by induction on (l, d)** ’ to describe an induction on the pair (l, d) , lexicographically ordered, where d is the number of occurrences of \cdot in τ and l is the number of occurrences of λ in τ .

Definition 4.5. For any $\tau \in \mathcal{L}_{\mathcal{X}\mathcal{C}}$, define $[x]\tau$ by induction on (l, d) .

1. (a) $[x]x$ is $(\mathbf{S}\cdot\mathbf{K})\cdot\mathbf{K}$
 (b) $[x]r$ is $\mathbf{K}\cdot r$ if r is a variable or constant distinct from x .
2. $[x](s\cdot r)$ is $(\mathbf{S}\cdot[x]s)\cdot[x]r$
3. $[x]\lambda z.s$ is $\mathbf{C}\cdot[z][x]s$

In this definition we allow the case that $z = x$ in the clause for $[x]\lambda z.s$.

Lemma 4.6. If $\tau \in \mathcal{L}_{\mathcal{X}\mathcal{C}}$ then $[x]\tau \in \mathcal{L}_{\mathcal{X}\mathcal{C}}$ and (1) is well defined, (2) contains no instances of λ , and (3) contains no free occurrences of x .

¹Nontriviality follows syntactically from the Church-Rosser property [HS08, Ch. A2], the cut-elimination theorem of [Gab11]; and it follows semantically from Scott’s famous model D_ω [HS08, Ch. 16], among others.

Proof. By induction on (l, d) . □

Lemma 4.7. *Let variable v not occur in t , then $[x](t[y/v]) = ([x]t)[y/v]$*

Proof. By induction on (l, d) . See the technical appendix A.5. □

Definition 4.8. Extend the notion of a valuation from Definition 2.11 so that

$$[[\mathbf{S}]]^v = [[\lambda xyz.((x \cdot z) \cdot (y \cdot z))]]^v \quad [[\mathbf{K}]]^v = [[\lambda xy.x]]^v \quad [[\mathbf{C}]]^v = [[\lambda xyz.((x \cdot z) \cdot y)]]^v$$

Theorem 4.9. *If $t \in \mathcal{L}_{\mathcal{C}}$, then for any $M = \langle F, v \rangle$, $[[x]t * s]^v \subseteq [[t[x/s]]]^v$*

Proof. By induction on (l, d) . See the technical appendix A.6. □

Definition 4.10. A model is **combinator complete** when for any $h_1, h_2, h_3 \in H$

$$(h_1 \bullet h_3) \bullet (h_2 \bullet h_3) = ((([\mathbf{S}]]^v \bullet h_1) \bullet h_2) \bullet h_3 \quad h_1 = ((([\mathbf{K}]]^v \bullet h_1) \bullet h_2)$$

$$\bigcap_{h \in H} \{w \mid w \circ h \subseteq (h_1 \bullet h) \bullet h_2\} = ((([\mathbf{C}]]^v \bullet h_1) \bullet h_2)$$

A frame F is combinator complete when it is faithful and each $\langle F, v \rangle$ is combinator complete.

Remark 4.11. Notice that no $h \in H$ can be empty if F is a non-trivial combinator complete frame. For if $\emptyset \in H$ then for any $h \in H$, $h = ((([\mathbf{K}]]^v \bullet h) \bullet \emptyset) \bullet \emptyset = \emptyset$, so then $H = \{\emptyset\}$ and $[[t]]^v = [[s]]^v = \emptyset$ for any t, s and v .

We could have equivalently defined combinator complete frame by requiring that, for any v and any x, y, z , $[[x]]^v = ((([\mathbf{K}]]^v \cdot x) \cdot y)^v$, $[[x \cdot z] \cdot (y \cdot z)]^v = ((([\mathbf{S}]]^v \cdot x) \cdot y) \cdot z)^v$ and $[[\lambda z.((x \cdot z) \cdot y)]]^v = ((([\mathbf{C}]]^v \cdot x) \cdot y)^v$. But 4.10 is preferable as it is independent of the syntax.

Theorem 4.12. *For any combinator complete $\langle F, v \rangle$, $[[t[x/s]]]^v \subseteq [[x]t \cdot s]^v$.*

Proof. Again, we proceed by induction on (l, d) . See the technical appendix A.7. □

Corollary 4.13. *For any combinator complete model M , $[[t[x/s]]]^v = [[\lambda x.t \cdot s]^v$.*

Proof. Since $\bullet \subseteq \circ$ we have that $[[\lambda x.t \cdot s]^v \subseteq [[\lambda x.t * s]^v$, and so Theorem 4.9 entails that $[[\lambda x.t \cdot s]^v \subseteq [[t[x/s]]]^v$.

And conversely:

$$\begin{aligned} [[t[x/s]]]^v &\subseteq [[x]t \cdot s]^v && \text{Thrm 4.12} \\ &\subseteq [[\lambda x.([x]t * x) \cdot s]^v && \text{Thrm 3.9, Lemma 2.20, Lemma 4.6} \\ &\subseteq [[\lambda x.t \cdot s]^v && \text{Thrm 4.9} \end{aligned}$$

□

We now have a means of characterising β -equality semantically.

Corollary 4.14. *If $t, s \in \mathcal{L}_\lambda$ then, $t \implies_\beta s$ iff $[[t]]^v \subseteq [[s]]^v$ for all combinator complete models.*

Proof. By 4.13 if $\langle t, s \rangle \in \beta$ then $[[t]]^v \subseteq [[s]]^v$ in all combinator complete models. Furthermore if $t \not\implies_\beta s$ then $[[t]]^v \not\subseteq [[s]]^v$ in the canonical model for β . It is not hard to verify that the canonical model (moreover, the canonical frame) is combinator complete. □

Corollary 4.15. *A frame is combinator complete iff it is β -sensitive*

Definition 4.16. A model is **fully extensional** when $h = \bigcap_{h' \in H} \{w \mid w \circ h' \subseteq h \bullet h'\}$ for all $h \in H$.

Remark 4.17. Looking at Definition 2.12 $h = \llbracket \mathbf{t} \rrbracket^v$ implies $\bigcap_{h' \in H} \{w \mid w \circ h' \subseteq h \bullet h'\} = \llbracket \lambda y.(\mathbf{t} \cdot y) \rrbracket^v$ for $y \notin \mathbf{t}$. So if a model is fully extensional then, for any \mathbf{t} and any v , $\llbracket \mathbf{t} \rrbracket^v = \llbracket \lambda x(\mathbf{t} \cdot x) \rrbracket^v$ for x not free in \mathbf{t} . This implies, by reasoning similar to Corollary 3.11, that $\bullet = \circ$.

Definition 4.18. Let $\eta_e = \{\langle \mathbf{t}[y:-\mathbf{s}], \mathbf{t}[y:-\lambda x.(\mathbf{s} \cdot x)] \rangle \mid \mathbf{r}, \mathbf{s} \in \mathcal{L}_\lambda \text{ and } x \text{ not free in } \mathbf{s}\}$; and let $\eta_c = \{\langle \mathbf{t}[y:-\lambda x.(\mathbf{s} \cdot x)], \mathbf{t}[y:-\mathbf{s}] \rangle \mid \mathbf{r}, \mathbf{s} \in \mathcal{L}_\lambda \text{ and } x \text{ not free in } \mathbf{s}\}$; and finally let $\beta\eta = \beta \cup \eta_e \cup \eta_c$

Theorem 4.19. *If $\mathbf{t}, \mathbf{s} \in \mathcal{L}_\lambda$ then, $\mathbf{t} \Longrightarrow_{\beta\eta} \mathbf{s}$ iff $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ for all fully extensional combinator complete models.*

Proof. It is straightforward to verify (see Remark 4.17) that $\mathbf{t} \Longrightarrow_{\beta\eta} \mathbf{s}$ implies that $\llbracket \mathbf{t} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ in all fully extensional, combinator complete models. Conversely, if $\mathbf{t} \not\Longrightarrow_{\beta\eta} \mathbf{s}$ then $\llbracket \mathbf{t} \rrbracket^v \not\subseteq \llbracket \mathbf{s} \rrbracket^v$ in the canonical model for $\beta\eta$, it is not hard to verify that it is combinator complete and fully extensional. \square

5 Further Work

There are numerous other semantics for untyped λ -calculus, and it is a matter of great interest to compare them to the one given here. A detailed comparison is not possible in this paper, but a few key differences can be noted. The semantics of this paper is *complete*. Unlike e.g. Scott models [HS08, Ch.16], we interpret the λ -operator directly. That is, we do not merely present an extensional combinatory algebra that only interprets application and the combinators **S** and **K**. The models and frames of this semantics are ordered, but do not necessarily have a bottom element (the canonical model provides a denotation for each term, and there is no ‘bottom’ term). Finally, we can distinguish intensional from extensional λ -equality semantically.

The characterisation of equality offered by Section 4 is still lacking in providing guidance for explicitly constructing a nontrivial model of lambda equality. We know that λ -calculus is not trivial, so we can use Theorem 3.9 to conclude that such a model exists. But it would be valuable to construct and compare models of intensional and extensional λ -equality.

Finally, the semantics of this paper potentially provides a new framework for obtaining semantics for ‘non-standard’ λ -calculi. By altering the structure of frames and the semantic definition 2.12 we can validate and invalidate different reduction and equality rules. Of particular interest are frames where H is as close to $\mathcal{P}(W)$ as possible, and the behaviour of λ -terms interpreted in these frames is determined by structural properties of \bullet and \circ . This relates to the issue mentioned above of explicitly constructing a nontrivial model within this framework. It is preferable to construct one where H is a simple as possible, perhaps isomorphic to $\mathcal{P}(W)$, (see 4.11 for a reason not to make $H = \mathcal{P}(W)$). Carrying such a construction through is a natural next step.

A Technical Appendix

A.1 Theorem 2.7

Suppose that $\mathbf{t}_1 \Longrightarrow_{\Gamma} \mathbf{t}_2$, where $\mathbf{t}_1, \mathbf{t}_2 \in \mathcal{L}_\lambda$. We argue that any such derivation can be converted into a derivation that $\mathbf{t}_1 \longrightarrow_{\Gamma} \mathbf{t}_2$.

We first argue that any application of (η^*) or (sub) can be pushed in front of (i.e. towards the end of the derivation) an application of any other rule or eliminated entirely.

- If \mathbf{s}' is derived from \mathbf{s} by an application of any rule, then

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s}] \longrightarrow_{\Gamma} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{(s * y)}] \longrightarrow_{\Gamma} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{(s' * y)}]$$

may be replaced by:

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s}] \longrightarrow_{\Gamma} \mathfrak{t}[\mathbf{x}:-\mathbf{s}'] \longrightarrow_{\Gamma} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{(s' * y)}]$$

- The case where $\mathfrak{t}'[\mathbf{x}:-\mathbf{s}]$ is derived from $\mathfrak{t}[\mathbf{x}:-\mathbf{s}]$ is similar. Except the following three special cases:

1.

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s} \cdot \mathbf{r}] \xrightarrow[\text{(\eta^*)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{(s * y)} \cdot \mathbf{r}] \xrightarrow[\text{(\beta)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\mathbf{s * r}]$$

may be replaced by

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s} \cdot \mathbf{r}] \xrightarrow[\text{(sub)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\mathbf{s * r}]$$

2.

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s * r}] \xrightarrow[\text{(\eta^*)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{(s * y) * r}] \xrightarrow[\text{(\beta^*)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\mathbf{s * r}]$$

may be replaced by

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s * r}]$$

3.

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s}] \xrightarrow[\text{(\eta^*)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{(s * y)}] \xrightarrow[\text{(\alpha)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{z}.\mathbf{(s * z)}]$$

may be replaced by:

$$\mathfrak{t}[\mathbf{x}:-\mathbf{s}] \xrightarrow[\text{(\eta^*)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{z}.\mathbf{(s * z)}]$$

- By a similar reasoning it follows that *(sub)* can be pushed in front of any other rule, with the exception of the special case of the derivation segment

$$\mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{s} \cdot \mathbf{r}] \xrightarrow[\text{(sub)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{s * r}] \xrightarrow[\text{(\beta^*)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\mathbf{s}[\mathbf{y}/\mathbf{r}]]$$

which may be replaced by:

$$\mathfrak{t}[\mathbf{x}:-\lambda\mathbf{y}.\mathbf{s} \cdot \mathbf{r}] \xrightarrow[\text{(\beta)}]{\longrightarrow_{\Gamma}} \mathfrak{t}[\mathbf{x}:-\mathbf{s}[\mathbf{y}/\mathbf{r}]]$$

It follows that any derivation may be replaced by a derivation where the last application is an instance of *(\eta)* or *(sub)*, if either appears in the derivation at all. Since *(\eta)* and *(sub)* introduce an instance of $*$, if $\mathfrak{t}_2 \in \mathcal{L}_\lambda$ then no instances of *(\eta)* or *(sub)* occur in the derivation. Furthermore, since $\mathfrak{t}_1 \in \mathcal{L}_\lambda$ it follows that the derivation contains no instances of *(\beta^*)* or occurrences of $*$. This implies that $\mathfrak{t}_1 \longrightarrow_{\Gamma} \mathfrak{t}_2$.

A.2 Proof of Theorem 2.16

We show only (β) and (η^*) here, the others are equally straightforward.

$$\begin{aligned}
& \llbracket \lambda x. t \cdot s \rrbracket^v && \text{Definition 2.12} \\
& = \llbracket \lambda x. t \rrbracket^v \bullet \llbracket s \rrbracket^v && \text{Definition 2.12} \\
& = \bigcap_{h \in H} \{ w \mid w \circ h \subseteq \llbracket t \rrbracket^{v[x \mapsto h]} \} \bullet \llbracket s \rrbracket^v && \llbracket s \rrbracket^v \in H \\
& \subseteq \{ w \mid w \circ \llbracket s \rrbracket^v \subseteq \llbracket t \rrbracket^{v[x \mapsto \llbracket s \rrbracket^v]} \} \bullet \llbracket t \rrbracket^v && \bullet \subseteq \circ \\
& \subseteq \{ w \mid w \bullet \llbracket s \rrbracket^v \subseteq \llbracket t \rrbracket^{v[x \mapsto \llbracket s \rrbracket^v]} \} \bullet \llbracket t \rrbracket^v && \text{Definition 2.10} \\
& \subseteq \llbracket t \rrbracket^{v[x \mapsto \llbracket s \rrbracket^v]} && \text{Lemma 2.15} \\
& = \llbracket \phi[x/s] \rrbracket^v \\
& \\
& \llbracket t \rrbracket^v \subseteq \bigcap_{h \in H} \{ w \mid w \circ h \subseteq \llbracket t \rrbracket^v \circ h \} && \text{Definition 2.10} \\
& = \bigcap_{h \in H} \{ w \mid w \circ h \subseteq \llbracket t * x \rrbracket^{v[x \mapsto h]} \} && \text{x not free in } \llbracket t \rrbracket^v \\
& = \llbracket \lambda x. (t * x) \rrbracket^v && \text{Definition 2.12}
\end{aligned}$$

A.3 Proof of Theorem 3.7

First, note that $s \implies_{\Gamma}^{\zeta_f} r$ implies $t[x:-s] \implies_{\Gamma}^{\zeta_f} t[x:-r]$.

Now, we argue by induction on t we show that $w \in \llbracket t \rrbracket$ (i.e. $t \in w$) if and only if $w \in \llbracket t \rrbracket^v$.

– t is a variable x . Then $\llbracket x \rrbracket = v(x) = \llbracket x \rrbracket^v$ by the definition of v . Similarly, if t is a constant c .

– t is $t_1 \cdot t_2$.

Suppose $t_1 \cdot t_2 \in w$, and consider the worlds w_{t_1} and w_{t_2} in W_λ . If $s_1 \in w_{t_1}$ and $s_2 \in w_{t_2}$ then by Definition 3.3, $t_1 \implies_{\Gamma}^{\zeta_f} s_1$ and $t_2 \implies_{\Gamma}^{\zeta_f} s_2$. Thus $t_1 \cdot t_2 \implies_{\Gamma}^{\zeta_f} s_1 \cdot s_2$ and $s_1 \cdot s_2 \in w$. Then by the definition of \bullet_λ we have that $w \in w_{t_1} \bullet_\lambda w_{t_2}$. Furthermore, $w_{t_1} \in \llbracket t_1 \rrbracket$ and so by the induction hypothesis, $w_{t_1} \in \llbracket t_1 \rrbracket^v$. Similarly $w_{t_2} \in \llbracket t_2 \rrbracket^v$. Hence $w \in \llbracket t_1 \cdot t_2 \rrbracket^v$ by Definition 2.12.

Conversely, suppose that $w \in \llbracket t_1 \cdot t_2 \rrbracket^v$. Then there are w_{s_1}, w_{s_2} such that $w_{s_1} \in \llbracket t_1 \rrbracket^v$ and $w_{s_2} \in \llbracket t_2 \rrbracket^v$ and $w \in w_{s_1} \bullet_\lambda w_{s_2}$. By the induction hypothesis $w_{s_1} \in \llbracket t_1 \rrbracket$ and $w_{s_2} \in \llbracket t_2 \rrbracket$. Then $s_1 \implies_{\Gamma}^{\zeta_f} t_1$ and $s_2 \implies_{\Gamma}^{\zeta_f} t_2$. Furthermore, by the construction of \bullet_λ , $s_1 \cdot s_2 \in w$ and hence $t_1 \cdot t_2 \in w$.

– t is $t_1 * t_2$. Similar to the case for \cdot .

– t is $\lambda x. s$.

Suppose $\lambda x. s \in w_1$. Suppose that $w_3 \in w_1 \circ_\lambda w_2$, and that $w_2 \in h$ for some $h \in H_\lambda$, then $h = \llbracket r \rrbracket$ for some term r . By (ass) and ζ_f we have that $r \implies_{\Gamma}^{\zeta_f} c$ and $c \implies_{\Gamma}^{\zeta_f} r$ for some c . So $h = \llbracket c \rrbracket$ and $c \in w_2$. By the construction of \circ_λ , $\lambda x. s * r \in w_3$ and so $s[x/c] \in w_3$ by (β^*) , i.e. $w_3 \in \llbracket s[x/c] \rrbracket$. By the induction hypothesis $\llbracket s[x/c] \rrbracket = \llbracket s[x/c] \rrbracket^v$. Furthermore by Lemma 2.15 $\llbracket s[x/c] \rrbracket^v = \llbracket s \rrbracket^{v[x \mapsto \llbracket c \rrbracket^v]}$. But by the definition of v , $\llbracket c \rrbracket^v = \llbracket c \rrbracket$, and so $w_3 \in \llbracket s \rrbracket^{v[x \mapsto \llbracket c \rrbracket]}$. But $h = \llbracket c \rrbracket$ so $w_3 \in \llbracket s \rrbracket^{v[x \mapsto h]}$. Thus $w_1 \in \{ w \mid \forall h \in H_\lambda. w \circ_\lambda h \subseteq \llbracket s \rrbracket^{v[x \mapsto h]} \} = \llbracket (\lambda x. s) \rrbracket^v$. Hence, $\llbracket \lambda x. s \rrbracket \subseteq \llbracket (\lambda x. s) \rrbracket^v$

Conversely, suppose that $\lambda x. s \notin w_r$ for some r . Let y be a variable not free in r or s and consider the worlds w_y and $w_{r * y}$. If $s[x/y] \in w_{r * y}$ then $r * y \implies_{\Gamma}^{\zeta_f} s[x/y]$, so $\lambda y. (r * y) \implies_{\Gamma}^{\zeta_f} \lambda y. (s[x/y])$. But by our choice of y , (η) entails that $r \implies_{\Gamma}^{\zeta_f} \lambda y. (r * y)$. So $r \implies_{\Gamma}^{\zeta_f} \lambda y. s[x/y]$, which contradicts our initial supposition that $\lambda x. s \notin w_r$, therefore $s[x/y] \notin w_{r * y}$. In other words

$w_{r^*y} \notin \|\mathbf{s}[x/y]\|$. Therefore, by the induction hypothesis, $w_{r,y} \notin \llbracket \mathbf{s}[x/y] \rrbracket^v$. Since $\llbracket y \rrbracket^v = \|y\|$, it follows by Lemma 2.15 that $w_{r,y} \notin \llbracket \mathbf{s} \rrbracket^{v[x \mapsto \|y\|]}$. But clearly $w_{r^*y} \in w_r \circ_\lambda w_y$, so it follows that $w_r \notin \{w \mid \forall h \in H_\lambda, w \circ_\lambda h \subseteq \llbracket \mathbf{s} \rrbracket^{v[x \mapsto h]}\}$. By the semantics of $(\lambda y.s)$, this means that $w_r \notin \llbracket (\lambda y.s) \rrbracket^v$. Hence, since every $w \in W_\lambda$ is w_r for some r , $\llbracket (\lambda x.s) \rrbracket^v \subseteq \|\lambda x.s\|$.

A.4 Proof of Lemma 3.8

We must show that for any valuation v' and any term \mathbf{t} that $\llbracket \mathbf{t} \rrbracket^{v'} \in H$. By the definition of a valuation $\llbracket \mathbf{x} \rrbracket^{v'} \in H$ for any variable \mathbf{x} . So if $\llbracket \mathbf{t} \rrbracket^{v'} \notin H$ then

$$\llbracket \mathbf{t} \rrbracket^{v[x_1 \mapsto \llbracket \mathbf{x}_1 \rrbracket^{v'} \dots x_n \mapsto \llbracket \mathbf{x}_n \rrbracket^{v'}]} \notin H$$

where $\mathbf{x}_1 \dots \mathbf{x}_n$ are the free variables of \mathbf{t} . Now, by assumption, v is such that every $h \in H$ is $\llbracket \mathbf{s} \rrbracket^v$ for some \mathbf{s} . It follows then that we can choose $\mathbf{s}_1 \dots \mathbf{s}_n$ such that $\llbracket \mathbf{s}_i \rrbracket^v = v[x_i \mapsto \llbracket \mathbf{x}_i \rrbracket^{v'}]$, and so:

$$\llbracket \mathbf{t} \rrbracket^{v[x_1 \mapsto \llbracket \mathbf{s}_1 \rrbracket^v \dots x_n \mapsto \llbracket \mathbf{s}_n \rrbracket^v]} \notin H$$

This entails, by Theorem 2.15 that $\llbracket \mathbf{t}[x_i/\mathbf{s}_i] \rrbracket^v \notin H$. But this contradicts the assumption that $\{\llbracket \mathbf{t} \rrbracket^v \mid \mathbf{t} \text{ is a term}\} = H$.

A.5 Proof of Lemma 4.7

By induction on (l, d) .

– If \mathbf{t} is \mathbf{x} then $\mathbf{x}[y/v] = \mathbf{x}$ and so

$$\begin{aligned} [\mathbf{x}]\mathbf{x} &= (\mathbf{S}\cdot\mathbf{K}\cdot)\mathbf{K} && \text{Def. 4.5} \\ &= ([\mathbf{x}]\mathbf{x})[y/v] && y \notin (\mathbf{S}\cdot\mathbf{K}\cdot)\mathbf{K} \end{aligned}$$

– If \mathbf{t} is \mathbf{y} then $\mathbf{y}[y/v] = v$ and $[\mathbf{x}]\mathbf{y} = \mathbf{K}\cdot\mathbf{y}$. So:

$$\begin{aligned} [\mathbf{x}]v &= \mathbf{K}\cdot v && \text{Def. 4.5} \\ &= (\mathbf{K}\cdot\mathbf{y})[y/v] && y \notin \mathbf{K} \\ &= ([\mathbf{x}]\mathbf{y})[y/v] \end{aligned}$$

– The case where \mathbf{t} is some variable other than \mathbf{x} or \mathbf{y} is similar.

– If \mathbf{t} is $\mathbf{s}\cdot\mathbf{r}$ then the result follows easily by the induction hypothesis.

– If \mathbf{t} is $\lambda z.s$, including the case where \mathbf{z} is \mathbf{x} , then

$$\begin{aligned} [\mathbf{x}](\mathbf{t}[y/v]) &= \mathbf{C}\cdot[\mathbf{z}][\mathbf{x}](\mathbf{s}[y/v]) && \text{Def. 4.5} \\ &= \mathbf{C}\cdot([\mathbf{z}][\mathbf{x}]\mathbf{s})[y/v] && \text{ind. hyp, Lemma 4.6} \\ &= (\mathbf{C}\cdot[\mathbf{z}][\mathbf{x}]\mathbf{s})[y/v] && y \notin \mathbf{C} \\ &= ([\mathbf{x}]\mathbf{t})[y/v] \end{aligned}$$

A.6 Proof of Theorem 4.9

By induction on (l, d) . We appeal to known facts about β -reduction and the Completeness Theorem 3.9.

– $\mathbf{t} = \mathbf{x}$. Then $[\mathbf{x}]\mathbf{t} * \mathbf{s}$ is $((\mathbf{S}\cdot\mathbf{K}\cdot)\mathbf{K})\cdot\mathbf{s}$, and it is easy to show that for any M

$$\llbracket ((\mathbf{S}\cdot\mathbf{K}\cdot)\mathbf{K})\cdot\mathbf{s} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$$

(see e.g. [HS08, p.26] and use 2.21). And given the validity of (β^*) we can also show that $\llbracket ((\mathbf{S}\cdot\mathbf{K}\cdot)\mathbf{K}) * \mathbf{s} \rrbracket^v \subseteq \llbracket \mathbf{s} \rrbracket^v$ in any M .

– The argument is similar for the case where $\mathbf{t} = \mathbf{y} \neq \mathbf{x}$.

– $\mathbf{t} = \mathbf{t}_1 \cdot \mathbf{t}_2$. Then:

$$\begin{aligned} \llbracket ((\mathbf{S} \cdot [\mathbf{x}]\mathbf{t}_1) \cdot [\mathbf{x}]\mathbf{t}_2) * \mathbf{s} \rrbracket^v &\subseteq \llbracket ([\mathbf{x}]\mathbf{t}_1 \cdot \mathbf{s}) \cdot ([\mathbf{x}]\mathbf{t}_2 \cdot \mathbf{s}) \rrbracket^v && \text{Def. 4.8} \\ &\subseteq \llbracket \mathbf{t}_1[\mathbf{x}/\mathbf{s}] \cdot \mathbf{t}_2[\mathbf{x}/\mathbf{s}] \rrbracket^v && \text{Ind. Hyp.} \\ &= \llbracket (\mathbf{t}_1 \cdot \mathbf{t}_2)[\mathbf{x}/\mathbf{s}] \rrbracket^v \end{aligned}$$

– If \mathbf{t} is $\lambda \mathbf{y} \cdot \mathbf{r}$, then choose a variable \mathbf{z} that does not occur in \mathbf{r} or \mathbf{s} . Now, \mathbf{s} and $[\mathbf{x}]\mathbf{s}$ contain fewer instances of λ than \mathbf{t} (Lemma 4.6), so given Theorem 3.9 we may apply the induction hypothesis as follows:

$$\begin{aligned} \llbracket (\mathbf{C} \cdot [\mathbf{y}][\mathbf{x}]\mathbf{r}) * \mathbf{s} \rrbracket^v &\subseteq \llbracket \lambda \mathbf{z} \cdot (((\mathbf{C} \cdot [\mathbf{y}][\mathbf{x}]\mathbf{r}) * \mathbf{s}) * \mathbf{z}) \rrbracket^v && \text{Thrm 2.21} \\ &\subseteq \llbracket \lambda \mathbf{z} \cdot (([\mathbf{y}][\mathbf{x}]\mathbf{r} \cdot \mathbf{z}) * \mathbf{s}) \rrbracket^v && \text{Def. 4.8, Thrm 3.9} \\ &\subseteq \llbracket \lambda \mathbf{z} \cdot ([\mathbf{x}]\mathbf{r}[\mathbf{y}/\mathbf{z}] * \mathbf{s}) \rrbracket^v && \text{Ind. Hyp.} \\ &\subseteq \llbracket \lambda \mathbf{z} \cdot (\mathbf{t}[\mathbf{y}/\mathbf{z}, \mathbf{x}/\mathbf{s}]) \rrbracket^v && \text{Ind. Hyp.} \\ &= \llbracket \lambda \mathbf{y} \cdot (\mathbf{t}[\mathbf{x}/\mathbf{s}]) \rrbracket^v \end{aligned}$$

A.7 Proof of Theorem 4.12

We can now proceed by induction on (l, d) .

– $\mathbf{t} = \mathbf{x}$. Then $\mathbf{x}[\mathbf{x}/\mathbf{s}] = \mathbf{s}$ and it is not hard to see that the definition of combinator completeness (4.10) implies that $\llbracket \mathbf{s} \rrbracket^v = \llbracket ((\mathbf{S} \cdot \mathbf{K}) \cdot \mathbf{K}) \cdot \mathbf{s} \rrbracket^v$.

– The argument is similar for the case where $\mathbf{t} = \mathbf{y} \neq \mathbf{x}$.

– $\mathbf{t} = \mathbf{t}_1 \cdot \mathbf{t}_2$. Then:

$$\begin{aligned} \llbracket (\mathbf{t}_1 \cdot \mathbf{t}_2)[\mathbf{x}/\mathbf{s}] \rrbracket^v &= \llbracket \mathbf{t}_1[\mathbf{x}/\mathbf{s}] \rrbracket^v \bullet \llbracket \mathbf{t}_2[\mathbf{x}/\mathbf{s}] \rrbracket^v \\ &\subseteq \llbracket ([\mathbf{x}]\mathbf{t}_1 \cdot \mathbf{s}) \rrbracket^v \bullet \llbracket ([\mathbf{x}]\mathbf{t}_2 \cdot \mathbf{s}) \rrbracket^v && \text{Ind. Hyp.} \\ &= (\llbracket [\mathbf{x}]\mathbf{t}_1 \rrbracket^v \bullet \llbracket \mathbf{s} \rrbracket^v) \bullet (\llbracket [\mathbf{x}]\mathbf{t}_2 \rrbracket^v \bullet \llbracket \mathbf{s} \rrbracket^v) \\ &= (\llbracket \mathbf{S} \rrbracket^v \bullet \llbracket [\mathbf{x}]\mathbf{t}_1 \rrbracket^v) \bullet \llbracket [\mathbf{x}]\mathbf{t}_2 \rrbracket^v \bullet \llbracket \mathbf{s} \rrbracket^v && \text{Def 4.10} \\ &= \llbracket ((\mathbf{S} \cdot [\mathbf{x}]\mathbf{t}_1) \cdot [\mathbf{x}]\mathbf{t}_2) \cdot \llbracket \mathbf{s} \rrbracket^v \rrbracket^v && \text{Def. 2.12} \\ &= \llbracket ([\mathbf{x}]\mathbf{t}_1 \cdot \mathbf{t}_2) \cdot \mathbf{s} \rrbracket^v && \text{Def. 4.5} \end{aligned}$$

and the result follows as above.

– Suppose \mathbf{t} is $\lambda \mathbf{y} \cdot \mathbf{r}$. Let \mathbf{z} be chosen so that it does not occur in \mathbf{t} or \mathbf{s} . Then using Lemma 2.20:

$$\begin{aligned} \llbracket \lambda \mathbf{y} \cdot (\mathbf{r}[\mathbf{x}/\mathbf{s}]) \rrbracket^v &= \llbracket \lambda \mathbf{z} \cdot (\mathbf{r}[\mathbf{y}/\mathbf{z}, \mathbf{x}/\mathbf{s}]) \rrbracket^v \\ &\subseteq \llbracket \lambda \mathbf{z} \cdot ([\mathbf{x}](\mathbf{r}[\mathbf{y}/\mathbf{z}]) \cdot \mathbf{s}) \rrbracket^v && \text{Ind. Hyp.} \\ &= \llbracket \lambda \mathbf{z} \cdot (([\mathbf{x}]\mathbf{r})[\mathbf{y}/\mathbf{z}] \cdot \mathbf{s}) \rrbracket^v && \text{Lemma 4.7} \\ &\subseteq \llbracket \lambda \mathbf{z} \cdot (([\mathbf{y}][\mathbf{x}]\mathbf{r} \cdot \mathbf{z}) \cdot \mathbf{s}) \rrbracket^v && \text{Ind. Hyp.} \\ &\subseteq \llbracket (\mathbf{C} \cdot [\mathbf{y}][\mathbf{x}]\mathbf{r}) \cdot \mathbf{s} \rrbracket^v && \text{Def. 4.10} \\ &= \llbracket ([\mathbf{x}]\lambda \mathbf{y} \cdot \mathbf{r}) \cdot \mathbf{s} \rrbracket^v && \text{Def. 4.5} \end{aligned}$$

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