Modelling spatial-temporal dynamics of cyanobacteria abundance in lakes by integrating cellular automata and genetic programming

Yuqing Lin¹, Min Wang¹, Qiuwen Chen¹*, Arthur E Mynett¹
¹ CEER Nanjing Hydraulic Research Institute, Nanjing 210029, China
Corresponding author: qwchen@nhri.cn

Abstract

Cyanobacteria blooms are a serious problem around the world and have caused severe ecological and social-economic damage. Data-mining models have proven effective at predicting such blooms; however, few of them can provide the spatial dynamics. Although process-based numerical models do provide a way to model, such approach often involves too many parameters to be calibrated. This study took the case of Taihu Lake and developed a model that embedded a data-mining technique into a cellular automata configuration, so as to obtain the spatial-temporal dynamics of cyanobacteria blooms. The lake was divided into polygons in accordance with the monitoring stations by using the Voronoi method. Data on flows, water quality and phytoplankton were collected from monitoring stations inside Taihu Lake. Genetic programming was applied to establish predictive formulations for the cyanobacteria population dynamics in relation to flow and water quality variables by using the collected data. The formulations accounted for local interactions between polygons as the evolution rules for the cellular automata. The results show that in this way CA models are able to predict both approximate magnitudes as well as accurate timing of cyanobacteria blooms quite well for all areas except for regions with lower cyanobacteria population. Overall the CA model shows very promising performance in capturing the spatial-temporal dynamics of algal abundance in lakes.

1 Introduction

Blooms of cyanobacteria are a global environmental concern. Lake Taihu, located in a region of China undergoing rapid economic development, has experienced accelerating eutrophication over the past three decades (Qin et.al., 2007, 2010). The cyanobacteria population has increased considerably and accounts for nearly 85% of the summer phytoplankton biomass (Chen et al., 2003). The dominant species *Microcystis* is usually toxic and associated with severe human health effects (Jia et al., 2016).
Cyanobacteria produce taste and odor problems in drinking water supplies, disrupt tourism and fishing, and cause economic losses (Yang et al., 2008; Guo et al., 2007).

The mechanisms causing cyanobacterial blooms are complicated, involving hydrodynamic, chemical and biological processes and interactions. During the past decades, considerable efforts have been made to develop models for predicting cyanobacteria blooms. Such models have proved helpful in ecosystem analysis and better understanding ecological interactions. Nowadays, process–based modelling and data mining approaches both are commonly used methods. Process–based models have achieved remarkable success in various lakes because they can describe the growth and outbreak processes of cyanobacteria quite well (Hamrick, 1992; Cole and Buchak, 1995; Moll and Radach, 2003; Gal et al., 2009; Zhang et al., 2013; Chen et al., 2014). However, a substantial amount of physical, chemical and biological data is needed to calibrate each detailed process description. This causes difficulties in practical application and leads to uncertainty of the predictive capabilities. Alternatively, many data mining techniques such as artificial neural networks, genetic programming and fuzzy logic have been applied to ecological case studies, in particular when the hydrodynamic and transport processes can be neglected (Chan et al., 2007; Chen and Mynett, 2003; Maier et al., 1998; Recknagel et al., 2003; Whigham and Recknagel, 2001). However, predictive models based on data mining techniques often focus on one particular lake only, which causes the portability of the models to be poor. Moreover, data-mining models usually cannot provide the spatial dynamics. Therefore, the prediction of cyanobacteria dynamics in large lakes with heterogeneous spatial properties still remains an extremely challenging topic in ecohydraulics research.

Cellular automata models are set up by subdividing the study space into cells and taking each cell as a separate subdomain with its internal rules on e.g. growth and decay processes. The CA approach can overcome the shortcomings of data mining models and reflect the spatial heterogeneity and local interactions (Chen et al., 2002). In recent years, CA has been widely used in ecological modelling, including rainforest dynamics (Alonso and Sole, 2000), population dynamics of animals (Chen and Mynett, 2003), competitive growth of underwater macrophyte species (Chen et al., 2002), vegetation evolution (Ye et al., 2010) and more.

In this study, genetic programming (GP) using the dataset of measurements from Lake Taihu was used to develop the internal rule-based system of the cellular automata model to predict the spatial-temporal dynamics of cyanobacteria blooms. The lake was divided into polygons by connecting the monitoring sites using the Voronoi method (Lin, 2014). For each site, GP was applied to establish a predictive formulation for cyanobacteria population dynamics in relation to physical-chemical variables. These formulations include local interactions between polygons to serve as evolution rules of cellular automata.

2 Materials and methods

2.1 Study area and data collection

Lake Taihu, situated in the South of the Yangtze River Delta (E30°56’–31°33’, N119°54’–120°36’) is the third largest shallow freshwater lake in China (Figure. 1). The surface area is 2,338 km^2 and the water depth ranges from 1.0 to 2.5 m. The lake has a drainage area of 36,500 km^2 and more than 30 canals and rivers discharge water into the lake. The inflow rivers mainly come from the Western lake. The Taipu River is the main river discharging water from the lake. The Wangyu River delivers Yangtze River water to the lake. In recent years, due to excessive wastewater discharge from factories, industry and agriculture, severe cyanobacteria blooms have occurred from May to October.
Monthly data on surface water (0.0–0.5 m) from 2008 to 2012 were collected from 31 sites in the whole lake (Figure 1). For each site, physical, chemical and biological parameters were measured, including water temperature (WT), Secchi depth (SD), pH, nitrate-N (NO$_3$-N), ammonia-N (NH$_3$-N), phosphate-P (PO$_4$-P) and cyanobacteria. Before developing any model, the data were linearly interpolated to produce daily values. The principle characteristics are given in Table 1.

### 2.2 Methodologies

Genetic Programming (GP) belongs to the class of evolutionary algorithms (EAs), which evolve tree structures and find optimized solutions (Koza, 1994, 1996). Banzhaf (1998) define GP as the direct evolution of programs or algorithms for the purpose of inductive learning. The method builds on the genetic algorithm (GA) concept, and represents an initialized population using LISP lists, which are specific tree structures. Subsequently, the population evolves and is optimized by means of genetic operators (a.o. crossover and mutation). The approach has been widely used in a variety of fields such as engineering science, economics science, medical science and environmental science.

In this study, GP was applied for predicting cyanobacteria populations in Lake Taihu by means of physical and chemical data. The coefficient of determination (r$^2$) of a linear regression and visual comparison between predicted and measured data were used to determine the best performing predictive models generated by GP. The model was designed for 2-day ahead forecasting by imposing a time lag of two days between input and output data. For all applications of the GP, an initial population of 100 and a maximum number of generations of 80 were chosen based on trial and error.

Cellular automata constitute a mathematical system in which many simple components interact locally to produce globally complicated patterns of behaviour (Chen et al., 2002). A cellular automata system usually consists of a regular lattice of sites (cells or automata). Each site has some properties that are updated in discrete time steps according to local evolution rules, which are functions of the states of the cell itself and its neighbours (Chen and Mynett, 2006).
2.3 Model setup

The Thiessen polygons based on the Voronoi method were used to set up the cells in the study area. In the CA model the Moore neighbourhood configuration is applied and the local evolution rules are built by GP from the measurement data obtained. Since the measured cyanobacteria population is affected by the neighbouring sites, assuming that the amount of nutrients and cyanobacteria population are constant in the whole lake, we eliminated the influence of neighbouring sites according to the weighted average method and build a generic predictive model under the condition of no winds, which is given by Eq. (1):

\[
\bar{V} = \frac{\sum_{i=1}^{N} (V_i \times S_i)}{S}
\]

(1)

where \(\bar{V}\) is the average value of each variable; \(i\) is the site; \(N\) is the number of the site; \(S_i\) is the area that each site represents; \(S\) is the total area of Lake Taihu. The converted data are used to produce the generic predictive rule set. Then for each site the rule set is applied to predict the next level of cyanobacteria. Considering that the cyanobacteria at time step \(t+2\) are affected by the cyanobacteria at time step \(t\), the growth rate \((R)\) is chosen as the output variable and the pH, water temperature, Secchi depth, NH\(_3\)-N, NO\(_3\)-N, PO\(_4\)-P as the input variables. The growth rate formula is given by Eq. (2):

\[
R_i^{t+2} = (7.66 + NO_3_i^{t} + 0.0441 \times WT_i^{t} - pH_i^{t} - 0.14 \times PO_4_i^{t}) / (1.2 + (NO_3_i^{t})^2)
\]

(2)

where \(R_i^{t+2}\) represents the growth rate for site \(i\) at the time step \(t+2\); \(NO_3_i^{t}\) represents the NO\(_3\)-N values for site \(i\) at the time step \(t\); \(WT_i^{t}\) represents the water temperature for site \(i\) at the time step \(t\); \(pH_i^{t}\)
represents the pH for site \( i \) at the time step \( t \); \( PO_{i} \) represents the PO\(_4\)-P values for site \( i \) at the time step \( t \). For each site the measured cyanobacteria values are given as initial values. The predicted values of cyanobacteria are calculated iteratively according to Eq. (3):

\[
C_{i}^{t+2} = R_{i}^{t+2} + C_{i}^{t} \tag{3}
\]

where \( C_{i}^{t+2} \) represents the predicted values of cyanobacteria for site \( i \) at the time step \( t+2 \); \( C_{i}^{t} \) represents the values of cyanobacteria for site \( i \) at the time step \( t \). Then according to Eq. (4) the cyanobacteria for each site are updated to become the initial values at the next time step

\[
C_{i}^{t+2} = a_{i}C_{i}^{t+2} + \sum a_{j}C_{j}^{t+2} \tag{4}
\]

where \( a_{i} \) is the weight for site \( i \), \( a_{j} \) is the weight for neighbouring sites. \( C_{j}^{t+2} \) represents the values of cyanobacteria for neighbouring site \( j \) at time step \( t+2 \). In Lake Taihu, the three prevailing winds are from the Southeast in spring and summer, Northeast in autumn, and Northwest in winter (Ma et al., 2009). The neighbouring sites are identified according to the flow field determined by the wind. Based on many trial experiments, \( a_{i} \) was found to be 0.7; \( a_{j} \) is calculated according to the inverse distance between the affected site and its neighbouring site, while \( \sum a_{j} \) is 0.3.

3 Results

3.1 Temporal predictive modelling of cyanobacteria by CA

Figure 2 shows a comparison between the measured and predicted results for eight sites representing the eight parts identified within Lake Taihu. For site 2, site 6 and site 22 with hyper-eutrophication and very high cyanobacteria, the CA models could predict the magnitude and timing of cyanobacteria blooms well, and \( r^2 \) values were well above 0.54. For site 11, site 17 and site 29 with medium-eutrophication and high cyanobacteria, the \( r^2 \) of the model fit were between 0.35 and 0.48. Although these \( r^2 \) values are relatively low, the CA models could still predict the outbreak of cyanobacteria blooms well. For sites 12 and 24 with light eutrophication and low cyanobacteria levels, the peak values of cyanobacteria predicted by the CA model were much higher than the measured results and the highest \( r^2 \) was 0.12. This may be due to the fact that the Eastern Lake connects to the river outflow so the cyanobacteria flow out of the water body in reality, leading to the predictive values being higher than observed values.

The results of the CA model were compared with those of the site-specific model (Zhang et al., 2014) and a genetic programming (GP) model that did not use any CA procedure (i.e. without the calculation of Eq. (4)). The comparisons are given in Table 2 to Table 4. Although the \( r^2 \) in the CA models was relatively lower than the site-specific model, the CA models could better capture the outbreak of cyanobacteria in most areas except for the worst results, in the Eastern Lake. Compared to the GP models that did not account for the influence from neighbouring sites, the results from the CA models turned out to perform much better. For site 2, site 6 and site 22, the CA models achieved better predictive results. For site 12 and site 24, the timing of cyanobacteria blooms lagged in the GP model and the peaks were much higher than the measured results. Although the peak values in the CA models were substantially reduced, the timing of the peaks was still adequate. For site 11 and site 17, the peak values of cyanobacteria in the GP models came out higher than the measured results. The CA models greatly improved the results. For site 29, the CA models improved the peaks and timing of cyanobacteria blooms only slightly.
Figure 2: Comparison between measured and predicted results in eight sites representing eight typical parts of Lake Taihu (model 1: GP models not considering the influences of neighbouring sites; model 2: Cellular automata prediction models considering the influences of neighbouring sites)

Table 2: R-square values between the measured and predicted results for four models in eight sites representing eight parts of Lake Taihu

<table>
<thead>
<tr>
<th>Sites</th>
<th>Site-specific model*</th>
<th>GP model without neighbouring sites</th>
<th>CA model</th>
</tr>
</thead>
<tbody>
<tr>
<td>Site 2</td>
<td>0.83</td>
<td>0.20</td>
<td>0.62</td>
</tr>
<tr>
<td>Site 6</td>
<td>0.83</td>
<td>0.22</td>
<td>0.56</td>
</tr>
<tr>
<td>Site 11</td>
<td>0.70</td>
<td>0.39</td>
<td>0.35</td>
</tr>
<tr>
<td>Site 12</td>
<td>0.77</td>
<td>0.11</td>
<td>0.08</td>
</tr>
<tr>
<td>Site 17</td>
<td>0.67</td>
<td>0.54</td>
<td>0.48</td>
</tr>
<tr>
<td>Site 22</td>
<td>0.78</td>
<td>0.14</td>
<td>0.54</td>
</tr>
<tr>
<td>Site 24</td>
<td>0.62</td>
<td>0.005</td>
<td>0.12</td>
</tr>
<tr>
<td>Site 29</td>
<td>0.73</td>
<td>0.11</td>
<td>0.40</td>
</tr>
</tbody>
</table>

* Site specific model developed by using the same data (Zhang et al., 2014).
3.2 Temporal predictive modelling of cyanobacteria by CA

The spatial cyanobacteria dynamics in four seasons during 2008–2012 calculated by the CA model are presented in Figure 3 which shows that CA models can capture the spatial patterns of cyanobacteria quite well compared to the observations, except that the predictive values in the Eastern Lake were higher than the measured values.

4 Discussion and conclusions

A spatial-temporal dynamic model of cyanobacteria blooms was developed using genetic programming to establish the transition rules from measurement data and integrate them into a cellular automata model set up for Taihu Lake, China. The resulting model proved to predict the magnitudes and timing of cyanobacteria blooms quite well for all areas except in the Eastern Lake which had a lower cyanobacteria population. Simultaneously, the model could capture the spatial dynamics of cyanobacteria and intuitively enhance our understanding of the spatial plaque formation mechanism of cyanobacteria blooms and help to improve the capability of cyanobacteria bloom management.

Clearly the site-specific models provided good results for each individual site, but did not provide a generic understanding of the underlying processes and key determining factors. The GP models based on aggregated data for all sites showed to overcome the disadvantages of site-specific models and turn out to have good portability. However, these models lack the ability to simulate spatial dynamics. In contrast, CA models can provide spatial dynamics, but the models produced from aggregated data gave worse results than the site-specific models. However, deploying GP to derive site-specific transition rules to be implemented into a spatially-explicit CA formulation, provides a generic modelling approach to site-specific conditions.

The evaluation criteria for models should not only focus on predictive capabilities at one particular site, but should also take into account the portability and generic interpretation. Overall, the results from the models employed in this study indicate that CA is a most effective method to deal with local interactions and model spatial variability. CA models not only consider the dynamic processes of cyanobacteria but also the spatial connection between the various sites, and have the capacity to simulate spatial-temporal dynamics. Compared to the traditional dynamic models for algal blooms based on two- or three-dimensional numerical simulation, this method avoids the complicated process of solving a great number of coupled partial differential equations, leading to higher
computational efficiency.

Genetic programming was used to formulate the transition rules for cyanobacteria population dynamics while the cellular automata approach was able to capture the spatial variability of bloom events. The results demonstrate that CA models can be used to forecast the magnitude, timing and location of cyanobacteria blooms by providing input on limnological time-series measurement data. The findings reveal that GP in combination with CA can provide a promising modelling approach in the field of spatial-temporal algal bloom forecasting.

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Reference


